http://www.toky.com.cn

Intelligent Temperature Controller User Manual

For TP-C Version



Features

⊙ Multi input signal and multi models for option.

- ⊙With measured display, control output, alarm output, analog output, RS485 communication, etc.
- ⊙ Multi PID algorithms for option, with auto tune function
- ⊙This product can be used in industrial machinery, machine tools, general measuring instruments and equipment.

National High-tech Enterprise/ National Standar	9	B	0	9	
Hotline : 400-0760-168	Version code :	KKTP-0	C01E-	A/1-20	201026

The instruction explain instrument settings, connections, name and etc, please read carefully before you use the temperature controller. Please keep it properly for necessary reference.

I. Safe Caution

▲ Warning

- When the failure or abnormal of products lead to a system of major accidents, please set the proper protection circuit in the external.
 Please don't plug in before completing all the wire.Otherwise it may lead to electric
- shock, fire, fault.

3) Not allow to use outside the scope of product specification, otherwise it may lead to fire,fault.

4) Not allow to use in the place where is inflammable and explosive gas.
5) Do not touch power terminal and other high voltage part when the power on otherwise you may get an electric-shock.
6) Do not remove, repair and modify this product, otherwise it may lead to electric shock, fire, fault.

▲ Caution

1) The product should not be used in a nuclear facility and human life associated

- medical equipment. 2) The product may occur radio interference when it used at home. You should take adequate countermeasures.
- The product get an electric shock protection through reinforced Insulation. When the product is embedded in the devices and wiring, please subject to the specification of embedded devices.
- In order to prevent surge occurs, when using this product in the place of over 30m indoor wiring and wiring in outdoor, you need to set the proper surge suppression
- circuitry. The product is produced based on mounting on the disk.In order to avoid to touch
- 5) The product is produced based on mounting on the disk in order to avoid to touch the wire connectors, please take the necessary measures on the product.
 6) Be sure to observe the precautions in this manual, otherwise there is a risk of a major injury or accident.
 7) When wiring, please observe the local regulation.
 8) To prevent to damage the machine and prevent to machine failure, the product is connected with power lines or large capacity input and output lines and other methods please install proper capacity fuse or other methods of protection circuit.
 9) Please don't put metal and wire clastic mixed with this product, otherwise it may lead to blectic shock fire fault
- to electric shock, fire, fault,
- Please tighten screw torque according to the rules. If not, it may lead to electric shock and fire.
- shock and fire.
 11) In order not to interfere with this products to dissipate heat, please don't plug casing around the cooling venthole and equipment.
 12) Please don't connect any unused terminal.
 13) Please do the cleaning after power off, and use the dry cleaning cloth to wipe away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoloration of the product.
 14) Please don't knock or rub the panel with rigid thing.
 15) The readers of this manual should have basic knowledge of electrical, control, communications.
- computer and communications
- computer and communications.
 16) The illustration, example of data and screen in this manual is convenient to understand,instead of guaranteeing the result of the operation.
 17) In order to use this product with safety for long-term,regular maintenance is necessary. The life of some parts of the equipments are by some restrictions, but the performance of some will change for using many years.
 18) Without prior notice, the contents of this manual will be change. We hope these is no any loopholes, if you have questions or objections, please contact us.

Caution of Install & Connection

CSRIMPORT

- Installation

- Installation

 This product is used in the following environmental standards.
 (IEC61010-1) [Overvoltage category II, class of pollution 2]

 This product is used in the following scope:environment, temperature, humidity and environmental conditions.Temperature:0~50°C;humidity: 45~85%RH; Environment condition:Indoor warranty.The altitude is less than 2000m.
 Please avoid using in the following places:

 The place will be dew for changing temperature; with corrosive gases and flammable gas; with vibration and impact; with water, oil, chemicals, smoke and steam facilities with dust, salt, metal powder; and with clutter interference, static electric and magnetic fields, noise; where has air conditioning or heating of air blowing directly to the site; where will be illuminated directly by sunlight; where accumulation of heat will happen caused by radiation.
- the site; where will be illuminated directly by sunlight; where accumulation of heat will happen caused by radiation.
 4) On the occasion of the installation, please consider the following before installation. In order to protect heat saturated, please ensure adequate ventilation space. Please consider connections and environment, and ensure that the products below for more than 50mm space. Please avoid to installed over the machine of the calorific value (Such as heaters, transformer, semiconductor operations, the bulk resistance). When the surrounding is more than 50, please using the force fan or cooling fans. But don't let cold air blowing directly to the product. In order to improve the anti interference performance and security, please try to stay away from high pressure machines and the product. The distance should be more than 200mm between the product and power line. power line.
- . Cable caution

- Cable caution :
 Please use specified compensation wire in the place of TC input; Please use insulated TC if the measured device is heated metal.
 Please use the cable of lesser resistance in the place of RTD input, and the cable (3 wire) must be no resistance difference, but the total length is within 5m.
 In order to avoid the effect of noise, please put the input dignal away from meter cable, power cable, load cable to wiring.
 In order to reduce the power cables and the load power cables on the effect of this product, please use noise filter in the place where easy to effect. You must install it on the grounding of the disk if you use the noise filter, and make the wiring to be shortest between noise filter output side and power connectors. Don't install fuse and switch on the wiring of noice filter output side, otherwise it will reduce the effect of noise filter.
- noise filter. 5) It takes 5s from input power to output.If there is a place with interlocking actions

- 5) It takes 5s from input power to output.If there is a place with interlocking actions circuit signal,please use timer relay.
 6) Please use twisted pair with a shield for analog output line, can also connect the common-mode coil to the front-end of the signal receiving device to suppress line interference if necessary, to ensure the reliability of signal.
 7)Please use twisted pair with a shield for remote RS485 communication cable, and deal with the shield on the host side earth, to ensure the reliability of signal.
 8) This product don't have the fuse; please set according to rated voltage 250V, rated current 1A if you need; fuse type:relay fuse.
 9) Please use suitable slotted screwdriver and wire. Terminal distance: 5.0mm. Screwdriver size: 0.6X3.5, length of slotted screwdriver >130mm. Recommended tightening torque: 0.5N.m. Proper cables: 0.25 ~ 1.65mm single cable/multiple core cable
- 10) Please don't put the Crimp terminal or bare wire part contact with adjacent connector.
- Model Illustration П.

woder mustration	
TP4	C: Version
	Blank: TC/RTD/mV/Rt input X: mA/V input
	10: Single input without RS485
	18: Single input with RS485
	B: One alarm C: Two alarms A: No alarm
	R: Relay output S:SSR output D:DC 4-20mA(It
	can be changed to analog output by ACT menu)
	K: SCR output (to be ordered)
	M:SSR/Relay (switched by ACT)
	Blank:No I:DC 4~20mA analog output (it can be
	changed to control output by ACT menu, available
	for size 6, 9)
0	Blank:AC/DC 100~240V
	F:AC/DC 24V(to be ordered)
	4:48H*48W*71L 7:72H*72W*71L

6:96H*48W*71L 9:96H*96W*71L

TP Series temperature controller

Ι.	M	od	e	s

Model	OUT1 control output		Alarm output		Analog output	Comm.	Auxilliary power	
	RELAY	SSR	4 ~ 20mA	AL1 OUT2	AL2	4 ~ 20mA	RS485	24V
TP4-DC18			•		•	0	•	•
TP4-DC10			•	•	•	0		•
TP4-RC18	•				•		•	
TP4-SC18		•		•	•		•	
TP4-MC10	٠	•		•	•			
TP7-DC18			•	•	•	0	•	•
TP7-DC10			•	•	•	0		•
TP7-MC18	٠	•			•		•	
TP7-MC10□	•	•		•	•			
TP6/9-IMC18	•	•	•	•	•	0	•	•
TP6/9-IMC10	•	•	•	•	•	0		•
TP6/9-DC18□		•	•			0	•	•
TP6/9-DC10		•	•	•	٠	0		•
TP6/9-MC18□	•	•			•		•	
TP6/9-MC10□	•	•		•	•			
	TP4-DC18 TP4-DC10 TP4-RC18 TP4-SC18 TP4-SC18 TP7-DC10 TP7-DC10 TP7-MC18 TP7-MC10 TP6/9-IMC10 TP6/9-DC10 TP6/9-MC18 TP6/9-MC10	Model RELAY RP4-DC18 RELAY TP4-DC10 TP4-DC10 TP4-RC18 • TP4-SC18 • TP4-SC18 • TP7-DC10 • TP7-DC18 • TP7-DC18 • TP7-MC18 • TP6/9-IMC18 • TP6/9-DC10 • TP6/9-DC10 • TP6/9-MC18 •	Model RELAY SSR TP4-DC18 TP4-RC10 TP4-RC18 • TP4-RC18 • TP4-RC18 • TP4-RC18 • TP7-DC18 • TP7-DC18 • TP7-MC18 • • TP6/9-IMC10 • • TP6/9-IMC10 • • TP6/9-DC108 • • TP6/9-MC18 • • TP6/9-MC18 • • TP6/9-MC10 • •	Model RELAY SSR 4 ~ 20mA TP4-DC18 • • TP4-DC10 • • • TP4-DC18 • • • TP4-C18 • • • TP4-SC18 • • • TP4-SC18 • • • TP7-DC18 • • • TP7-DC10 • • • TP7-MC18 • • • TP6/9-IMC18 • • • TP6/9-IMC18 • • • TP6/9-DC10 • • • TP6/9-MC18 • • • TP6/9-MC10 • • •	Model AL1 OUT2 TP4-DC18□ • • TP4-DC10□ • • TP4-RC18□ • • TP4-RC18□ • • TP4-SC18□ • • TP4-SC18□ • • TP4-SC18□ • • TP7-DC18□ • • TP7-DC18□ • • TP7-MC18□ • • TP7-MC18□ • • TP6/9-IMC18□ • • TP6/9-IMC18□ • • TP6/9-DC18□ • • TP6/9-DC18□ • • TP6/9-MC18□ • •	Model AL1 RELAY AL2 OUT2 AL1 OUT2 AL2 TP4-DC18 •	Model AL1 OUT2 AL2 4 ~ 20mA TP4-DC18 • <	Model All NULL All OUTZ All All All All All All All

□ : Blank: input signal is TC/RTD/Mv/Rt; "X" : input signal is 4 ~ 20mA/0 ~ 10V Standard configuration function

 $^{\odot}$: The meter has this function, but it is combined with another function. This series only have one loop 4~20mA output, but the user can modify menu ACT to set it as main control output or analog output.

IV. Specifications

1. Electrical paramete	ars:				
Sampling rate	2 times per second				
Relay capacity	AC 250V /3A Life of rated load>100,000 times				
Power supply AC/DC 100 ~ 240V(85-265V)					
Power consumption < 6VA					
Environment	Indoor use only, temperature: 0~50°C no condensation, humidity < 85%RH, altitude<2000m				
Storage enenvironment -10 ~ 60°C, no condensation					
2					

TOKY

SSR output	DC 24V pulse voltage, load<30mA		
Current output	DC 4 ~ 20mA load<500Ω, temperature drift 250PPM		
Communication port	RS485 port Modbus-RTU protocol, max input 30 units		
Insulation impedance	Input, output, power VS meter cover > $20M\Omega$		
ESD	IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.Criteria B		
Pulse traip anti-interference	IEC/EN61000-4-4 ±2KV perf.Criteria B		
Surge immunity	IEC/EN61000-4-5 ±2KV perf.Criteria B		
Voltage drop & short interruption immunity	IEC/EN61000-4-29 0% ~ 70% perf.Criteria B		
Isolation voltage	Signal input, output, power: 1500VAC 1min <60V low voltage circuit: DC500V,1min		
Total weight	About 400g		
Cover material	The shell and panel frame PC/ABS (Flame Class UL94V-0)		
Panel material	PC		
Power failure memory	10 years, times of writing: 1 million times		
Safety Standard	<code>IEC61010-1</code> Overvoltage category Π , pollution level 2 , <code>level</code> $\Pi($ Enhanced insulation)		

2. Measured signal specifications :

Input type	Symbol	Measuring range	Resolution	Accuracy	Input impedance/ auxiliary current	Comm. parameter code
K1	51	$-50 \sim 1200$	-50 ~ 1200 1°C 0.5%F.S±3digits		>500KΩ	0
K2	85	$-50.0 \sim 999.9$	0.2°C	0.5%F.S±1℃	>500kΩ	16
J1]	$0 \sim 1200$	1℃	0.5%F.S±3digits	>500KΩ	1
J2	51	$0.0 \sim 999.9$	0.2℃	0.5%F.S±1°C	>500KΩ	17
E1	Εl	$0 \sim 850$	1℃	0.5%F.S±3digits	>500KΩ	2
E2	53	$0.0\sim 850.0$	0.3℃	0.5%F.S±1℃	>500KΩ	18
T1	٤l	$-50 \sim 400$	1℃	0.5%F.S±3℃	>500KΩ	3
T2	٤2	$-50.0 \sim 400.0$	0.4℃	0.5%F.S±3℃	>500KΩ	19
В	Ь	$250 \sim 1800$	1℃	1%F.S±2°C	>500KΩ	4
R	r	$-10 \sim 1700$	1℃	1%F.S±2°C	>500KΩ	5
S	5	$-10 \sim 1600$	1℃	1%F.S±2°C	>500KΩ	6
N1	- 1	$-50 \sim 1200$	1℃	0.5%F.S±1℃	>500KΩ	7
N2	5-	$-50.0 \sim 999.9$	0.2°C	0.5%F.S±1℃	>500KΩ	20
PT100-1	PE1	$-200.0 \sim 600.0$	0.2℃	0.5%F.S±0.3℃	0.2mA	8
PT100-2	PF5	$-200 \sim 600$	1℃	0.5%F.S±3digits	0.2mA	21
JPT100-1	JPEI	$-200.0 \sim 500.0$	0.2°C	0.5%F.S±0.3°C	0.2mA	9
JPT100-2	76FS	$-200 \sim 500$	1℃	0.5%F.S±3digits	0.2mA	22
CU50-1	ี	$-50.0 \sim 150.0$	0.2°C	0.5%F.S±3℃	0.2mA	10
CU50-2	CU52	$-50 \sim 150$	1℃	0.5%F.S±3℃	0.2mA	23
CU100-1	CUOI	$-50.0 \sim 150.0$	0.2℃	0.5%F.S±1℃	0.2mA	11
CU100-2	2003	$-50 \sim 150$	1°C	0.5%F.S±3digits	0.2mA	24
$0\sim 50 mV$	8 <u>0</u>	-1999 \sim 9999	12bit	0.5%F.S±3digits	>500kΩ	12
$0\sim 400\Omega$	۳ť	$-1999 \sim 9999$	12bit	0.5%F.S±3digits	0.2mA	13
* 4 \sim 20mA	ñ8	$-1999 \sim 9999$	12bit	0.5%F.S±3digits	<50Ω	14
$* 0 \sim 10V$	<u></u>	-1999 \sim 9999	12bit	0.5%F.S±3digits	>1MΩ	15
: Need to indicate the input signal requirement when the order is made.						

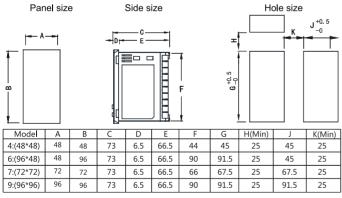
3. Isolation diagram:

	Pow	er supply	
1	×	#	¥
(I) Control output	MCU(Ⅱ) Measure input	Relay alarm output	Analog output communication port (I) auxiliar power
		11	

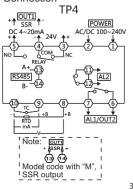
"//": Isolation

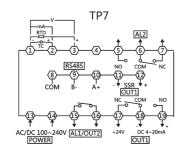
V. Dimension

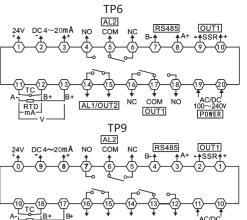
Note : When the auxiliary power supply between(I)&(II)is used as the power supply of external sensor, if the sensor is non-isolated, it does not isolate.



VI. Connection

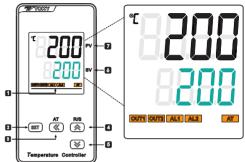






AC/DC 100~240 POWER RTD AL1/OUT2 NC COM NO

VII. Panel Illustration

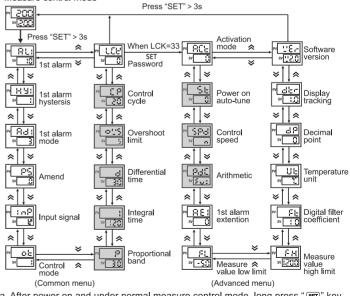


No.	Symbol	Name	Function
	OUT1	OUT1 (orange)	Main control output indicator, lights on when output ON
	OUT2	OUT2 (orange)	Cooling output indicator, lights on when output ON.
1	AL1	Alarm 1# (orange)	1st alarm output indicator, lights on when alarm output, lights off when no alarm output.
	AL2	Alarm 2# (orange)	2nd alarm output indicator, lights on when alarm output, lights off when no alarm output.
	AT	AT indicator (orange)	Auto tune indicator, lights on when it is under auto tune status.
2	SET	SET key	Menu key/confirm key, to enter or exit the modification mode, or to confirm and save the modified parameter.
3	«	Shift/AT key	Activate key/ shift key/ AT auto tune key (in measure and control mode, long press to enter/exit auto tune)
4	*	Add key/R/S	Add key, in measure and control mode,long press to shift RUN/STOP mode, or check the menu in reverse order.
5	*	Reduce key	Reduce key, check the menu in sequence
6	SV	Display (green)	Set value / parameter display window, the control is stopped when it displays "STOP"
7	PV	Display (white)	Measured value/ parameter code display window

VIII. Operation process and menu illustration

1. Operation process & method

Measure control mode



- a. After power on and under normal measure control mode, long press "

 more than 3s to enter the menu parameters checking mode.
 b. In the menu checking mode, press "

 is under the menu parameters check the menu parameters of the menu param
- b. In the menu checking mode, press (a) "key to check the line of a state of the line of the
- e. In the parameter modifing mode, after the modification, press " er " to save the modified parameter, and exit to menu checking mode. 4

// TOKY

- f. In the normal measure control mode, short press " ()" to enter SV value modifing status. The way of modifing SV value is same as that of modifing menu parameters.
- In the normal measure control mode, long press " AT " key more than 3s to enter auto tune state. During auto tune, PV value needs to be lower than SV g value.

h. In the normal measure control mode, long press " R/S " key more than 3s to enter or exit STOP model.

IX. Menu Illustration

: No mater what model, what control mode it is, it will always display these

parameters.

: According to different model, control mode, these parameters will be hidden. 1. Regular Menu

Note Product Product	1. F	Regula	r Me	nu		
1 8.: ALI 1st alarm value, note: the minus is dealed as absolute value when it is as a deviation value. FL - FH 10 2 MSU HVI 1st alarm mode note: when hit is as a deviation value. 0 - 1000 1 3 API OUT2 (cooling output), should set the value (ADI-0) (Close alarm function). When ADI-6, and ADI-0 (Close Alarm function). When ADI-6, and ADI-0, and ADI-0, and ADI-6, and ADI-0,	No.	Symbol	Name	Illustration	Setting	Factory
2 HSI: HYI 1st alarm mystersis 0 - 1000 1 3 Ref 1017 Cooling output, should set the value (1) Date 0 (dose starm function), When AD156, 2nd alarm function is invelid. 0 - 12 3 4 Ref ALI Cooling output, should set the value (1) Date 0 (dose starm function), When AD156, 2nd alarm function is invelid. 0 - 1000 1 6 Ref HI Coling output, should set the value absolute value when it is as a deviation value. 0 - 0 1000 6 Ref Philos Anmend value, display value= actual measured value + amend value 1499 - 9999 0 7 PS PS Armend value, display value= actual measured value + amend value 1499 - 9999 0 8 In-P INP Optional input signal. Note: after selecting the parameter: SU-ONOFF containg control, relevant parameter: DB. 1100 11 Philos 11 10 11	1	RL I	AL1			-
Instructure Ist alarm mode note: when AL1 is used as: AD1=0 (close alarm function). When AD1=6, AD1=0 (close alarm function). The alarm function function function function. The alarm function function function function. The alarm function function function function function. The alarm function function function function function. The alarm function function function function. The alarm function function function function function. The alarm function function function function function. The alarm function functi	2	893	HY1		0~1000	1
4 R.2 A12 2nd alarm value, note: the minuus is dealed as absolute value when it is as deviation value. FL - FH 5 5 M32 HV2 2nd alarm value when it is as deviation value. 0 ~ 1000 1 6 R42 HV2 2nd alarm mode 0 ~ 6 4 7 PS PS Amend value display value= actual measured value arraneters: SVAL1HY1AL2HY2P,OVS,DB. refer for impla parameters: SVAL1HY1AL1H2HY2P,OVS,DB. refer for impla parameters: SVAL1HY1AL1HY1AL1HY2P,OVS,DB. refer for impla parameters: SVAL1HY1AL1HY1AL1HY1AL1HY2P,OVS,DB. refer for impla parameters: SVAL1HY1AL1HY1AL1HY1AL1HY1AL1H			AD1	1st alarm mode,note: when AL1 is used as OUT2 (cooling output), should set the value AD1=0 (close alarm function). When AD1>6,		
6 842 102 2 nd alarm mode 0 ~ 6 4 7 95 PS Amero value, display value = actual measured value 199 - 999 0 8 IvP Value + amero value, display value = actual measured value 199 - 999 0 8 IvP Optional input signal, Note: after sateling the value is meters: baller the value is meters: baller the value is meters: baller the value is meters: P, I. D. OVS, CP, ST, SPD, PDC. K1 9 Control mode, 0.00N/OFF heating control (ceoling control, relevant parameter: DB, need to set PT when it is used for compressor control. 0 ~ 5 1 0/UT2 will output through AL 1 relay, relevant parameter: B, I. D. OVS, CP, ST, SPD, PDC. 0 ~ 5 1 10 8 - 5 PID cooling, relevant parameter: B, I. D. OVS, CP, ST, SPD, PDC. AUTO-AM AUTO-AM 11 p P roportional band, the smaller the value is, the faster the system responds otherwise, it is work of the value is, the stronger the integral action is, otherwise, it is weaker. When D=0, no relf cantrol is, otherwise, it is weaker. When D=0, no differential action. 0 ~ 9999 30 11 p P reportional band, the sampler the value is, the stronger the integral action units. 0 ~ 9999 30 12 <t< td=""><td>4</td><td>805</td><td>AL2</td><td>2nd alarm value, note: the minus is dealed as</td><td>FL ~ FH</td><td>5</td></t<>	4	805	AL2	2nd alarm value, note: the minus is dealed as	FL ~ FH	5
6 Ref 10 2 - 6 4 7 PS Product Amend value (sipply value= actual measured value + amend value -1999 - 9999 0 8 1x-2 INP Signal, please property set below relevant parameters: SVAL, 1YH, 2L, YUZ, PVOS, DB. (singla parameters: SVAL, 1YH, 2L, YYZ, PVOS, DB. (singla parameter); SVAL, YYH, 2L, YYZ, YYZ, YYZ, YYZ, YYZ, YYZ, YYZ, YY	5	835	HY2	2nd alarm hystersis	0 ~ 1000	1
7 PS PS Value + amend value Page 5 393 0 8 LxP PNP Signal page- mainters: SVAL 1, PH AL2, PH 2, PA/SVAD, BM (eque 3) K1 9	6	895		2nd alarm mode	0~6	4
8 LoP INP Signal The Los of Sumary set below value with the graameters is blue parameters: SVAL1.HY1,AL2,HY2,POVS,DB. (gage 3) Signal parameters is blue parameters: SVAL1.HY1,AL2,HY2,POVS,DB. (gage 3) 9 oft Control mode, 0.ON/OFF heating control, relevant parameters: F. P. D.,OVS, OP, ST, SPD, PDC. 0 0 1 1 PD heating control, relevant parameters: DB. T. SPD, PDC. 0 0 -5 1 0 -5 T. S. PD, PDC. 0 0 -5 1 10 8-7 A.M. control manufactor the value is, the stronger the integral action is, otherwise, it is solver, When P=0, no PID control, unit same as PV 0 - 9999 30 11 p P Proportional band, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When I=0, no integral action. It is solver, When P=0, no PID control, unit same as PV 0 - 9999 30 12 1 Integral time, the gradier the value is, the stronger the integral action is, otherwise, it is weeker. When I=0, no integral action is solver. 0 - 9999 30 13 d D Differential time, the smaller the value is, the stronger the integral action is, otherwise, eg., pressure, speed, unit :s 0	7	PS	PS		-1999 ~ 9999	0
9 ot OT relevant parameter: DB, 1: PID heating control, relavant parameters: P. I. D., OVS, CP, ST, SPD, PDC. 0.~5 1 2: ON/OF cooling control(cooling control compressor control. 3:PID heating & cooling control(cooling control OUT2 will output through AL1 relay), relevant parameters: DB 5. PID cooling, relevant parameter: P. I. D., OVS, CP, ST, SPD, PDC. 0.~5 1 10 8-5 A.M. Auto-manual control switch, AUTO(0): auto control only; MAN(1) manual control only; AM(2): auto-manual shortcut switch 0.~9999 30 11 p P proportional band, the smaller the value is, the faster the system responds otherwise, it is slower. 0.~9999 30 12 1 Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When 1=0, no integral action, unit: s. 0.~9999 30 13 d D Differential mice, the stream set the value is, the stronger the differential action is, otherwise, it is weeker. When 1=0, no integral action. Set D=0 when controlling fast systems, e.g., pressure, speed, unit: s 0.~9999 30 14 ev.f5 OVS OVS release set the appropriate value according to the actual situation. 1.~200 20 15 C.P CP OUT2 relow output, cycle. Unit s 4.~200 20	8	inP	INP	signal, please properly set below relevant	signal para- meters table	Кl
10 R5 A-M control only: MAN(1): manual control only: AM(2): auto-manual shortcut switch AUTO-AM AUTO-AM 11 P P Proportional band, the smaller the value is, the faster the system responds, otherwise, it is weeker. When P=0, no PID control, unit same as PV 0 ~ 9999 30 12 I Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit: s 0 ~ 9999 30 14 c-*5 OVS Overshoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(svershoot limit), force to close output, to Vershoot limit, sorte to close output, according to the actual situation. 0 ~ 9999 5 15 CP CP OUT1 control cycle, 1: SSR control output, 4-200: relay control output. Unit: s 1 ~ 200 20 16 CPI CPI OUT2 cooling proportionally coefficient, the higher of value, the storager of cooling 0.1 ~ 100.0 10.0 18 d> DB Data function. 0001: SV value can' to modified. Output: SR control output setting, please change this parameter according to the actual situation. 0.0 ~ 20 0.00-2 0.0 19 LEU LCK CATorlo execution mode. Orealy or SSR control output. SSR control output. SR con	9	ot	от	relevant parameter: DB. 1: PID heating control, relavant parameters: P, I, D, OVS, CP, ST, SPD, PDC. 2: ON/OFF cooling control, relevant parameter DB; need to set PT when it is used for compressor control. 3:PID heating & cooling control(cooling control OUT2 will output through AL1 relay), relevant parameters: P, I, D, OVS, CP, CP1, PC, DB, ST, SPD, PDC. 4: Over temperature cooling output, relevant parameter: DB 5. PID cooling, relevant parameter: P, I, D, OVS, CP, ST, SPD, PDC.		1
11 p P faster the system responds otherwise, it is slower. When P=0, no PID control, unit same as PV 0 ~ 9999 30 12 I Integral time, the smaller the value is, the stronger the integral action, no integral action, noits. 0 ~ 9999 10 13 d D Differential time, the greater the value is, the stronger the differential action is, otherwise, it is weeker. When D=0, no pID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit, force to close output. The smaller this value is, the smaller the value is, the adjustment range is, the worse the control atbility is. Please set the appropriate value according to the actual situation. 0 ~ 9999 5 14 e5 OVS OUT1 control cycle, 1: SSR control output. 4-200. relay control output. Unit: s 1 ~ 200 20 15 C.P CPI OUT2 relay output cycle. Unit: s 4 ~ 200 100 10.0 16 SP: CPI OUT2 cooling proprotionality coefficient, the higher of value, the stronger of cooling according to the dectorent point Drosition. 1.~ 200 20 19 LCE LCK Control settering ont Drosition. 0 9999 0 20 SEt ACT Control execution mode. Oraling ont Drosition. 0 9999 0 21	10	8-5	A-M	control only; MAN(1): manual control only; AM(2): auto-manual shortcut switch	AUTO~AM	AUTO
12iIstronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s. Differential time, the greater the value is, the stronger the differential actiontion is, otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit: s0 ~ 99993014e.'.5OVSOvershoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit, during PID control process, oUVS covershoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit, during PID control output, 4-200: relay control output, Unit: s0 ~ 9999515C.PCPOUT1 control cycle, 1: SSR control output, 4-200: relay control output, Unit: s1 ~ 2002016C.P:CPIOUT2 relay output cycle. Unit: s4 ~ 200100~10018ds DBDBON/OFF control hystersis (positive and negative numbers work differenti); after change the INP setting, please change this parameter according to the decimal point position1000~100019LCELCKControl execution mode. Orelay or SSR control output. 1:SSR control output only. 2: 4-20mA ocontrol output, setting should comply with the setting should comply with the setting should comply with the setting should comply with the set as or or 1, 4-20mA output is used as retransimition output, for size 6/9 products.0-2 0.0-2 (0-3)20RCE ACT<	11	9	Ρ	faster the system responds, otherwise, it is slower.	0 ~ 9999	30
13 d D stronger the differential actiontion is, otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit: s 0 ~ 9999 30 14 o.**5 OV OVershoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the control stability is. Please set the appropriate value according to the actual situation. 0 ~ 9999 5 15 C.P CP OUT1 control cycle, 1: SSR control output, 4-200: relay control output. Unit: s 1 ~ 200 20 16 C.P: CPI OUT2 relay output cycle. Unit: s 4 ~ 200 20 17 PC PC OUT2 cooling proportionality coefficient, the higher of value, the stronger of cooling 0.1 ~ 100.0 10.0 18 ds DB ON/OFF control hystersis (positive and negative numbers work (the same); when OT=3, it is the dead zone for cooling control (positive and negative numbers work (the cam apoint position. -1000~1000 5 19 LCck Lock function. 0001:SV value can' to be modified. 0010: menu SV can be checked only, can' to be modified. 0033: can enter to advanced menu. 0123: menus reset to factory setting, neadto output. TisSR control output. 1: SSR control output.	12	;	I	stronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s.	0 ~ 9999	120
14 eVS when PV(measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the control stability is. Please set the appropriate value according to the actual situation. 0 ~ 9999 5 15 CP CP OUT1 control cycle, 1: SSR control output, 4-200: relay control output, Unit: s 1 ~ 200 20 16 CP: CP OUT2 relay output cycle, Unit: s 4 ~ 200 20 17 PC OUT2 cooling proportionality coefficient, the higher of value, the stronger of cooling 0.1 ~ 100.0 10.0 18 db DB ON/OFF control hystersis (positive and negative numbers work differently); after change according to the decimal point position. -1000~1000 5 19 LCE LCK Control execution 0001:SV value can't be modified. 0012: menus reset to factory setting, need to reboot. 0~9999 0 20 RCE ACT Control execution mode. 0:relay or SSR control output. 1:SSR control output, setting should comply with the selected configuration of the meter. 3: 4~20mA retransimition output, for size 4/7 products. 0~2 0 21 REI AEI 1 st alarm extensions function, refer to alarm output or size 4/7 products. 0~5 0 22 RE2 ACD	13	6	D	stronger the differential actiontion is otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit: s	0 ~ 9999	30
15 LP LP 4-200: relay control output. Unit: s 1 ~ 200 20 16 CP1 OUT2 relay output cycle. Unit: s 4 ~ 200 20 17 PC PC OUT2 cooling proportionality coefficient, the higher of value, the stronger of cooling 0.1 ~ 100.0 10.0 18 PC PC ON/OFF control hystersis (positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control (positive and negative numbers work differently); after change the lNP setting, please change this parameter according to the decimal point position. -1000~1000 5 19 LCE LCK Lock function. 0001:SV value can't be modified. 0010: menu SV can be checked only, can't be modified. 0012: menus reset to factory setting, need to reboot. 0~9999 0 2. Advanced menu illustration Setting range Factory range Factory control output for size 4/7 products. When this menu is set as 0 or 1, 4-20mA output is used as retransimition output for size 6/9 products. 0~2 0 21 RE1 AE1 1st alarm extensions function, refer to alarm extension function table 0~5 0 22 RE2 AE2 2nd alarm extensions function, refer to alarm extension function table 0~5 0 23 dP P Decimal point setting, m	14	oUS	ovs	when PV(measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the control stability is. Please set the appropriate value	0 ~ 9999	5
16 CP1 OUT2 relay output cycle. Unit: s 4 ~ 200 20 17 PC PC OUT2 cooling proportionality coefficient, the higher of value, the stronger of cooling 0.1 ~ 100.0 10.0 18 PC DB ON/OFF control hystersis (positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control (positive and negative numbers work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 5 19 LCE LCK Lock function. 0001:SV value can't be modified. 0010: menu SV can be checked only, can't be modified. 0010: menu SV can be checked only. can't be modified. 0012: menus reset to factory setting, need to reboot. 0~9999 0 2. Advanced menu-uillustration Setting range Factory setting. need to reboot. 0~9999 0 2. Advanced menu-uillustration Control execution mode. 0:relay or SSR control output 1:SSR control output for size 4/7 products. When the selected configuration of the meter. 3: 4~20mA complex. When this menu is set as 0 or 1, 4-20mA output is used as retransimition output for size 6/9 products. 0~5 0 21 AE1 1st alarm extensions function, refer to alarm extension function table 0~5 0 22 AE2 AE2 Ch alarm extensions function, refer to alarm extension some occasions, it can get a more stable control albe	15	C۶	СР		1 ~ 200	20
17 PL PL higher of value, the stronger of cooling 0.1 ~ 1000 100 18 ds DB ON/OFF control hystersis (positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control (positive and negative numbers work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 5 19 LEE LCK Lock function. 0001:SV value can't be modified. 0033: can enter to advanced menu. 0123: menus reset to factory setting, need to reboot. 0~9999 0 2.Advanced menu illustration Setting Factory range Factory range Factory range Factory (0~3) 0 20 RCE ACT Control execution mode. 0:relay or SSR control output. 1:SSR control output for size 4/7 products. When this menu is set as 0 or 1, 4-20mA output is used as retransimition output for size 4/7 products. When this menu is set as 0 or 1, 4-20mA output is used as retransimition output, for size 6/9 products. 0~2 0 21 RE1 1st alarm extensions function, refer to alarm extension function table 0~5 0 22 RE2 AE1 1st alarm extensions function, refer to alarm extension function table 0~3 0 23 ds DP Decimal point setting, maximum 1 decimal measured value. Note: after setting this value, whe	16	CP:	CP1	OUT2 relay output cycle. Unit: s	4 ~ 200	20
18 35 DB ON/OFF control hystersis (positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control (positive and negative numbers work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 5 19 LCE LCK Lock function. 0001:SV value can't be modified. 0010: menu SV can be checked only, can't be modified. 0012: menus reset to factory setting, need to reboot. 0~9999 0 2. Advanced menu illustration Setting range Factory setting. Control execution mode. 0:relay or SSR control output. 1:SSR control output only. 2: 4~20mA control output. 1:SSR control output for size 4/7 products. When this menu is set as 0 or 1, 4-20mA doutput is used as retransimition output for size 6/9 products. 0~2 0 21 RE1 AEI 1st alarm extensions function, refer to alarm extension function table 0~5 0 23 dP DP Decimal point setting, maximum 1 decimal measured value, his value, is unrelated with actual measured value. Note: after setting this value, on some occasions, it can get a more stable control (0~20) 0.0 ~ 2.0 (1.0 (10) 24 dE- FF Filter coefficient, the higher of value, when alarm setting value, is unrelated with actual measured value. Note: after setting this value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (1.0 (10) 23 dP	17	PC	PC		0.1 ~ 100.0	10.0
19 LEF LCK 0010: menu SV can be checked only, can't be modified. 0033: can enter to advanced menu. 0123: menus reset to factory setting, need to reboot. 0~9999 0 2. Advanced menu illustration Setting range Factory setting, need to reboot. 0~9999 0 2. Advanced menu illustration Setting range Control execution mode. 0:relay or SSR control output. 1:SSR control output only. 2: 4-20mA control output. 5etting should comply with the selected configuration of the meter. 3: 4-20mA control output, setting should comply with the selected configuration of the meter. 3: 4-20mA (0~3) 0 20 REF ACT Setting retransimition output for size 4/7 products. When this selected configuration of the meter. 3: 4-20mA control extension function rable 0~5 0 21 REF AE1 1st alarm extensions function, refer to alarm extension function table 0~5 0 22 PE2 AE2 2nd alarm extensions function, refer to alarm extensions, it can get a more stable control place for TC & RTD input 0~3 0 23 SP DP Decimal point setting, maximum 1 decimal measured value. Note: after setting this value on some occasions, it can get a more stable control ameasured value. Note: after setting this value, when alarm setting value is equal to SV set value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 1.0	18	రం	DB	ON/OFF control hystersis (positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control (positive and negative numbers work differently); after change the INP setting, please change this parameter	-1000~1000	5
No. Symbol Name Illustration Setting range Factory setting 20 RCE Control execution mode. 0:relay or SSR control output. 1:SSR control output only. 2: 4~20mA control output. 1:SSR control output of the meter. 3: 4~20mA (0~3) 0~2 20 REE ACT Setting should comply with the setted configuration of the meter. 3: 4~20mA output is used as retransimition output, for size 6/9 products. When this menu is set as 0 or 1, 4-20mA output is used as retransimition output, for size 6/9 products. 0~5 0 21 RE1 AE1 1st alarm extensions function, refer to alarm extension function table 0~5 0 23 dP DP Decimal point setting, maximum 1 decimal place for TC & RTD input 0~3 0 24 dE- DTR PV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note: after setting this value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (0~20) 1.0 (0~20) 25 FE FT Filter coefficient, the higher of value, the stronger of filter function 0 ~ 255 10 26 uu UT				0010: menu SV can be checked only, can' t be modified. 0033: can enter to advanced menu. 0123: menus reset to factory setting, need to reboot.	0~9999	0
Ref. Symbol value Control execution mode. 0:relay or SSR control output 1:SSR control output only. 2: 4-20mA control output. 1:SSR control output only. 2: 4-20mA control output. 1:SSR control output only. 2: 4-20mA control output, setting should comply with the selected configuration of the meter. 3: 4-20mA retransimition output for size 4/7 products. When this menu is set as 0 or 1, 4-20mA output is used as retransimition output, for size 6/9 products. 0~2 0 21 RE1 AET 1st alarm extensions function, refer to alarm (2) 0~5 0 22 RE2 AE2 2nd alarm extensions function, refer to alarm extension function table 0~5 0 23 d* DP Decimal point setting, maximum 1 decimal place for TC & RTD input 0~3 0 24 d* DTR display value, this value is unrelated with actual measured value. Note: after setting this value, when alarm setting value is equal to SV set value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (0~20) (10) 25 FE FT Filter coefficient, the higher of value, the stronger of filter function 0 ~ 255 10 26 uu LT Temperature unit: °C: Celsius degrees. °F: (25)°C (25)°C						Factory
21 AE1 (2) 1st alarm extensions function, refer to alarm extension function table 0~5 0 22 AE2 (2) Ch alarm extensions function, refer to alarm (2) 0~5 0 23 AE2 (2) Ch alarm extensions function, refer to alarm (2) 0~5 0 23 AE2 (2) DP place for TC & RTD input 0~3 0 24 AE- veter DV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control measured value. Note: after setting this value, when alarm setting value is equal to SV set value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (0~ 20) 1.0 (10) 25 Ft FT Filter coefficient, the higher of value, the stronger of filter function 0 ~ 255 10 26 uu LT Temperature unit: °C: Celsius degrees. °F: (25)°C (25)°C				Control execution mode. 0:relay or SSR control output. 1:SSR control output only. 2: 4~20mA control output, setting should comply with the selected configuration of the meter. 3: 4~20mA retransimition output for size 4/7 products. When	range 0~2	setting
22 AE2 (2) 2nd alarm extensions function, refer to alarm extension function table 0~5 0 23 dP DP Decimal point setting, maximum 1 decimal place for TC & RTD input 0~3 0 24 dE- PV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control measured value. Note: after setting this value, when alarm setting value is unrelated with actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (0~20) 1.0 (10) 25 FE FT Filter coefficient, the higher of value, the stronger of filter function 0 ~ 255 10 26 uu LT Temperature unit: °C: Celsius degrees. °F: (25)°C (25)°C	21	861		1st alarm extensions function, refer to alarm	0~5	0
23 d* DP Decimal point setting, maximum 1 decimal place for TC & RTD input 0~3 0 24 d* DF Decimal point setting, maximum 1 decimal place for TC & RTD input 0~3 0 24 d* DTR display value, this value is unrelated with actual measured value. Note: after setting this value, when alarm setting value is equal to SV set value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (10) (10) (10) 25 FE FT Filter coefficient, the higher of value, the stronger of filter function 0 ~ 255 10 26 uu UT Temperature unit: °C: Celsius degrees. °F: (25)°C (25)°C (25)°C	22	862	AE2	2nd alarm extensions function, refer to alarm	0~5	0
24 BE- FV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control measured value, this value is unrelated with actual measured value. Note: after setting this value, when alarm setting value is equal to SV set value, alarm output operation is subject to actual measured value. Set as 0 to close this function. 0.0 ~ 2.0 (1.0) 1.0 (1.0) 25 FE FT Filter coefficient, the higher of value, the stronger of filter function 0 ~ 255 10	23			Decimal point setting, maximum 1 decimal	0~3	0
25 FE FT Filter coefficient, the higher of value, the stronger of filter function $0 \sim 255$ 10 26 III III Temperature unit: °C: Celsius degrees. °F: $(25)^{\circ}C$ $(25)^{\circ}C$	24	dbr	DTR	PV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note: after setting this value, when alarm setting value is equal to SV set value, alarm output operation is subject to actual		
Carles III LIT Temperature unit: °C: Celsius degrees. °F: (25)°C (25)°C	25	۶٤	FT	Filter coefficient, the higher of value, the	0 ~ 255	10
	26	UΈ	UT		(25)℃ (26)℉	(25)°C

5

					Automatización	Industrial
No.	Symbol	Name		Illustration	Setting range	Factory setting
27	۶L	FL	Measure range be less than me	Refer to measured signal parameter table	-50	
28	۶x	FH	Measure range must be more tl	Refer to measured signal parameter table	1200	
29	ხინ	BRL		limit, note: when this value is higher high limit,it is reverse analog output	FL~FH	-50
30	5-8	BRH		limit, note: when this value is lower low limit, it isreverse analog output.	FL~FH	1200
31	oll	OLL		limit the output low limit current ralue must be less than high limit.	- 5.0~100.0	0
32	6UN	OLH	amplitude. Set va	limit the output high limit current alue must be greater than low limit.	0.0 ~ 105.0	100.0
33	SE	ST	normally after p	ation after power-on, 0: work ower-on, 1: automatically enter auto-tune status after power-on key to exit auto-tune.	0~1	0
34	SPJ	SPD	PID control spect 1 (s) slow, 2 (ss	ed adjustment,option: 0 (N) No ,) medium slow, 3(SSS)very slow,) medium fast, 6 (FFF) very fast	0~6	Ν
35	980	PDC	PID arithmetic;	ption: 0(FUZ): Advanced fuzzy 1(STD): normal PID arithmetic	0~1	FUZ
36	98	PT		art delay time, unit: s	0~9999	0
37	683	BAD	2 (19.2): 19200	Baud rate 0 (4.8): 4800 ; 1 (9.6): 9600; 2 (19.2): 19200		
38	899	ADD	Communication		0~247	1
39	P-83	PRTY	0:NO 1:ODD	Communication parity check setting, 0:NO 1:ODD 2:EVEN		
40	99C	DTC	1st bit function	data transport sequence 000; reserved; 2nd bit is byte ange; 3rd bit function reserved.	Refer to COM. protocol note③	0
41	CRS	CAE	parameter is on TC/RTD; Y:enab	User self-calibration enable function, this parameter is only for the input signals except TC/RTD; Y:enable the self-calibration parameters; N: don't use the self-calibration parameters.		
42	CRL	CAL	the low end sign YES to activate, the input signal l	ow limit input operation, after add al to the signal input terminal,flash after confirm and display OK, ow end calibration is completed.	YES/OK	YES
43	C88	САН	the high end sigr YES to activate,	igh limit input operation, after add nal to the signal input terminal,flash after confirm and display OK, the end calibration is completed.	YES/OK	YES
44	287	VER	Software versio	n		
			ters and output logi			
-		criptic	n: "☆" means HY, "	▲" means alarm value, "△" means S		
Alar cod						
1	Hig ala		absolute value		PV	
2	Lov ala		absolute value		→ PV	
3		igh lin Je ala	nit deviation rm	↓ ☆ A SV SV+AL	→ PV	
4	×L ala		it deviation value	SV-AL SV	→ PV	
5	ЖН	igh/lo	w limit deviation		⇒ PV	

CSRIMPORT

alam	SV-AL SV
※High/low limit deviation value alarm	SV-AL SV SV+AL PV
∺High/low limit interval value alarm	SV-AL SV SV+AL
Alarm mode	The below two alarm parameters(AL1,AL2) are used in combination, AL1 alarm output, AD2 must be set as 0
High and low limit absolute value interval alarm	ALL SV AL2 PV
※High and low limit deviation value interval alarm	SV-ALL SV SV-AL2 ≻ PV
※High limit absolute value and low limit deviation value interval alarm	$\begin{array}{c c} & & & & & \\ \hline & & & & & \\ \hline & & & & \\ \hline & & & \\ SV & Al1 & SV & Al2 \end{array} \rightarrow PV$
※High limit deviation value and low limit absolute value interval alarm	$\begin{array}{c c} & & & & & \\ \hline & & & & & \\ \hline & & & & \\ \hline & & & \\ AL1 & SV & SV+AL2 \end{array} \rightarrow PV$
High/low limit absolute value alarm	
High/low limit deviation value alarm	SVAL1 SV SV+AL2
	 ※High/low limit deviation value alarm ※High/low limit interval value alarm Alarm mode High and low limit absolute value interval alarm ※High and low limit deviation value interval alarm ※High limit absolute value and low limit deviation value and low limit deviation value interval alarm ※High limit deviation value and low limit absolute value alarm

When the alarm value with deviation alarm is set as a negative number, it will be dealed as an absolute value.

(2) Alarm extension function table

(Z) Ala										
AE1/AE2 value	Alarm handling method when it displays HHHH/LLLL	Power on, alarm inhibition								
0	Alarm status remains the same									
1	Forced alarm output	(As long as the alarm condition is met, alarm output immediately.)								
2	Forced alarm close	alarm output immediately.)								
3	Alarm status remains the same									
4	Forced alarm output	(After power on and before the PV value reaches the SV for the first time, the alarm								
5	Forced alarm close	will not output. After that alarm work normally)								
X. Kev f	X. Key function operation									

- X. Key function operation
 1. Stop mode

 Under the measure mode, long press " R/S " key to enter the STOP mode, SV window will display "STOP", main control output will stop or keep the minimum output.
 Under STOP mode, long press " R/S " key to exit STOP mode, press " () under STOP mode, long press " R/S " key to exit STOP mode, press " () under STOP mode, alarm output and retransimition output work normally.

 PID auto-tune operation:

 hear auto-tune operation:

Before auto-tune procedure, please switch off the control output load power, or set the meter as STOP mode.

2) Before auto-tune procedure, PV value should meet below condition: when it is PID heating control, PV needs to be much smaller than SV; when it is PID cooling control, PV needs to be much larger than SV. 6

// TOKY

- 3) Before auto-tune procedure, please set a proper alarm value or eliminate the alarm condition, in order to prevent the auto-tune procedure from being affected by alarm output.

- affected by alarm output.
 4) Set PID type and SV value; the factory default setting is fuzzy PID.
 5) Set as PID control, if there is OLL & OLH output limiting, please set the output to a proper range; factory default setting is OLL=0%, OLH=100%.
 6) Exit STOP mode, or switch on the load Power, immediately long press " AT " key to enter auto-tune mode, then the AT indicator light is on.
 7) The auto-tune procedure will take some time, in order not to affect auto-tune result, please don't modify the parameters or power-off.
 8) When AT light goes out, it automatically exits auto-tune mode, PID parameters will be updated automatically, and then the meter will control automatically and exactly.
 9) During the auto-tune procedure, below actions will cause the termination of the precess, long press "AT " key, measure beyond the scope, abnormal display, switch to STOP mode, power-off, etc.
 10)Note: In the occasions with output limiting operation, sometimes, even if the
- 10)Note: In the occasions with output limiting operation, sometimes, even if the auto-tune is carried out, the best PID parameters still cannot be obtained.
 11)Experienced users can set proper PID parameter according to experience.
 3.PID heating and proportional cooling control operation
- PID heating and proportional cooling control operation
 Set the control mode OT as 3.
 2)PID heating control acts on OUT1;proportional cooling control acts on OUT2.
 3) Proportional cooling control OUT2 outputs via AL1 alarm function terminals.
 4) Please set the cooling start hystersis DB to a value greater than 5, to ensure the cooling output will not affect the PID heating control.
 5) Please actions action of the problem of the problem
- Please change the cooling control cycle CP1 and the cooling proportionality coefficient to a proper value.
- 6) When PV value > SV+DB value, the cooling control start to effect; the bigger value of PV, the longer output time of OUT2
- Auto-manual switch function

 Enter common manual, set parameter A-M as "AM".
 - 2) After return back to measure control interface, press " 🐨 " key to switch auto-manual operation.
 - auto-manual operation.
 3) When it is switched to manual control, lower line LED will display output percentage: M0~M100 (corresponding to 0%~100%), press Add Key or Reduce Key to modify the output percentage.
 4) Before the switch from manual control to auto control, in order to ensure the smooth switch, please press Left Key to modify the SV value first.
 5) After the meter is rebooted, the default setting is manual control and output 0.
- 5. Fixed manual control function1) Set A-M parameter as "MAN"
 - 2) After return back to measure control interface, user can modify output
 - percentage by manual.
 - 3) After the meter is powered on again, the manual output percentage can be restored
- restored.
 6. Linear signal self calibration function operation

 Set up the INP type, and ensure it is one of these input 0 ~ 50mV, RT(0 ~ 400 Ω), 4 ~ 20mA and 0 ~ 10V.
 Add the input signal to the correct input channel.
 Enter menu low-limit calibration menu CAL, press "AT " to flash"YES"; and set the input signal to minimum value and input it to the meter.

 - After calibrating low-limit, enter the high-limit calibration menu CAH, and flash "YES".

 - YES.
 Set the input signal to maximum value and input it into the meter; when the "YES" is flashing, press " m " to ensure and save the calibrating value.
 After calibrating, enter menu CAE, change "N" to "Y" to enable the calibrating value; otherwise, it still use the factory default value.
 - The calibrated high-limit input linear signal value should not exceed the input standard value range ±10%.
- 9) If not satisfied with the calibrating result, could calibrate again.

XI. Checking methods of simple fault

Display	Checking methods
LLLL/HHHH	Checks whether the input disconnection and whether normal of FH/ FL value, working environment temperature and whether input signal is selected correctly.
XII. Comm	nunication procotol

Meter adoptS RS485 Modbus RTU communication protocol, RS485 half duplex

communication. Read function code 0x03, write function code 0x10/0x06. Adopt 16 digit CRC check, the meter does not return for error check Data frame format:

Data france it	mat.		
Start bit	Data bit	Stop bit	Check bit
1	8	1	Set in Menu PRTY
Handling of a	hnormal com	munication:	

landling of abnormal communication:

When abnormal response, put 1 on the highest bit of function code. For example: Host request function code 0x03,and slave response function code should be 0x83.

Error code 0x01-Illegal function: the function code sent from host is not supported by meter.

0x02—Illegal address:the register address designated by host beyond the address range of meter. 0x03—Illegal data: Date value sent from host exceeds the corresponding data range of meter. Communication cvcle :

Communication cycle is the time from host request to slave response data, i.e.: communication cycle is the time of request data sending +slave preparation time + response datay time + response return time, e.g.:9600 Baud rate:communication cycle of single measured data ≥250ms.

1. Read register

For example:Host reads integer SV(set value 200) The address code of SV is 0x2000, because SV is integer(2 dyte), seizes 1 data register. The memory code of decimal integer 200 is 0x00C8. Note: when reading data, should read DP value or confirm DP menu value first to ensure the decimal point postion, after that transform the read data to get the actual value. Conversely, it should transform the data to corresponding ratio before writing the data in meter.

	Host request (Read multi-register)											
1	2	3	4		5	6	<u></u>	7		8		
Meter ADD	Function code	Start ADD High bit	ADD	Start Data byte I ADD Length ow bit high bit		Data byte Length Iow bit		CRC code low bit		<pre>%CRC code high bit</pre>		
0x01	0x03	0x20	0x00) Ox	0x00		01	0x8F		0xCA		
	Slave normal answer(Read multi-register)											
1	2	3		4		5		6		7		
		D ()		Dutu			W.C.		24	CDC I		

Meter ADD	Function code	Data byte Length	Data high bit	Data low bit	CRC coc Iow bit	le XCRC code high bit					
0x01	0x03	0x02	0x00	0xC8	0xB9	0xD2					
Function co	Function code abnormal answer: (For example: host request ADD is 0x2011)										
	Slave abnormal answer(Read multi-register)										

1	2	3	4	5					
Meter ADD	Function code	Error code	XCRC code low bit	XCRC code high bit					
0x01	0x83	0x02	0xC0	0xF1					
2. Write multi-register									

For example: Host use 0x10 function code write SV (setting value 150) ADD code of SV is 0x2000, because SV is integer(2 dyte), seizes 1 data register. The hexadecimal code of decimal integer 150 is 0x0096.

													Aut	omatiz	RIMPORT
						Host re	que	st (write m	ulti-	registe	ər)				
1		2	3		4	5		6	-	7	8	9	_	10	11
Mete	er Fun	ction	Sta AD		Start ADD	Data b		Data byte Length			Data high			CRC ode	CRC code
AD		ode			_ow bit			low bit		ngth	bit	bi		v bit	high bit
0x0	1 0	(10	0x2	0	0x00	0x0	0	0x01	0>	<02	0x00) 0x9	6 0	x07	0xFC
					Slave	norma	ans	wer (write	mu	lti-reg	ister)	1			
1		2		3		4		5		6	,		7		8
Mete		nction	Star			rt ADD		Data byte			a byt				XCRC code
						gth high b	it I	ength		bit	low b		high bit		
	0x01 0x10 0x20 0x00 0x00							0x0)1		0x0A	1	0x09		
lost	write S	SV wit	h 0x0	6 fun	nction (set va									
	Host request (write single-register) 1 2 3 4 5 6 7											8			
	eter	Func				Start A	חח			o Data		/ CRC d	ode	×.c	o CRC code
	DD	COC			h bit	Low		high bit		w bit	1	low b			high bit
0:	x01	0x0)6	0x2	20	0x00)	0x00	0)	k96		0x02			0x64
						Slave	e noi	rmal answe	ər (write	singl	e-regis	ter)		
	1	-	2		3	4		5		6		7			8
	eter		ction		DD	AD		Data		Data		XCRC		※(CRC code
	DD		ode		h bit	Low		high bit	+	low b	It	low		-	high bit
0	x01	UX	:06		x20	0x00		0x00		0x96		0x02	<u> </u>		0x64
					Slave a	bnorm	al ar	nswer (wri	te s	ing l e-	regis	ter)			
	1		 		2			3	_	N/O	4	ode			5
Ν	/leter A	DD	Fi	unctio	on cod	e	Ern	or code		×C low	RC c bit	uae		CRC gh bi	code t
	0x01		-	Ô٧	86			0x02	-		DxC3		+ '"	-	A1
Nete		meter	's ado			ing tab		SAUL							u tak
					riable					Rea	ister	R/V	v	R	emark
	0x200				t value					1		R/V			
	0x2000 (48195) Set Value 0x2001 (48194) 1st alarm						AI 1			1	-	R/V			
	0x2002 (48195) 1st alarm value ALT								1		R/V				
	0x2003 (48196) 2nd alarm valueAL2							1		R/V					
	0x2004 (48197) 2nd alarm hysteresis HY2							1			_				
-								-		R/W R/W					
_	0x2005 (48198) Display low limit FL 0x2006 (48199) Display high limit FH							1		· ·	_				
								1		R/V	_				
_	0x200									1		R/V	_		
_	0x200			_	Analog output high limit BRH					1		R/V	_		
	0x200			_	Control output low limit OLL					1		R/V	_		
	0x200	· ·			Control output high limit OLH					1		R/V		fault	1 decimal poin
	0x200					ot limit				1		R/V			
	0x200							ead zone D		1		R/V	_		
	0x200					alue P		nt of cooling) PC	_		R/V	_	fault	1 decimal poin
-	0x200									1		R/V		nine	ering work
16	0x200)F (48	3208) PV	fuzzy	trackir	ng va	alue DTR		1	-	R			decimal point
17	0x201	.0 (48	3209) Me	easure	ed val	ue F	⊃V		1		R			
18	0x201	.1 (48	3210) Οι	itput p	ercenta	age	MV		1		R/V		~100	
19	0x201	.2 (48	3211) Au	to-Mar	nual sv	/itch	A-M		1	L	R/V	V 0:	Auto	; 1: Manual
								Reserve	Э						
						mode				1		R/V			
21	0x210			/		n mode			-	1		R/V			
								function A		1		R/V R/V	_		
23						n exter node C		function /	¬⊏2	2 1		R/V			
24 25						node O							_		
2.5	07210	,	5474	100	որուո	JUG AL				-		R/V		RUN	2:STP
26	0x210	06 (4	8455) RL	JN/ST	OP ope	ratio	on		1	L	R/V			auto-tune
															auto-tune
						pointD	Р			1		R/V			
						lay UT				1		R/V		5 (°	C)26(°F)
						stants				1		R/V			
						nal co	effici	ient P		1		R/V			cimal point
					egral t		D			1		R/V			cimal point
						al time				1		R/V		io de	cimal point
33						peed fi control		une SPD		1		R/V R/V		lo da	cimal point
35						control				-		R/V	_		cimal point
36						delay ti				1		R/V			cimal point
						input s						R/V			o signal table
						dress A						R/V			
39	0x211	.3 (4	8468) Co	mmun	ication	bau	ud rate BA		1		R			
40	0x211	4 (4	8469) Co	m. dat	a trans	fer s	equence [R			Note ③
						metic t	ype	PDC	_	1	L	R			
42					ck LCł					1		R			
					eter na					1		R			
					tput st					1		R		1	Note ②
4 - 1	11/211	0 / 4	0171		with ch		TV			1 1					

45 0x2119 (48474) Parity Check PRTY

R : Read only ; R/W : Read & write

Note: The register number is the address converted to decimal plus 1 and then the register identification code 4 is added in front; for example: the register number of the data address 0x2000 is 8192 + 1 = 8193 and then 4 is added in front; that is, the register number 48193;

Related applications can be seen, such as Siemens S7-200 PLC. Note (2): Measurement status indication. When the data bit is 1, it means execution, and when it is 0, it means no execution.

	D7	D6	D5	D4	D3	D2	D1	D0			
	STOP	НННН	LLLL	AT	AL2	AL1	OUT2	OUT1			
N	Note③: DTC communication data transmission sequence description										

20-- Reserve DTC :

> Byte transfer order: when it is 0, 1, 2, and when it is 1, 2, 1 - Reserve

- *16-bit CRC check code to get C program unsigned int Get_CRC(uchar *pBuf, uchar num)
 - unsigned i,j;
 - unsigned int wCrc = 0xFFFF;
 - for(i=0; i<num; i++)

}

- wCrc ^= (unsigned int)(pBuf[i]); for(j=0; j<8; j++)

if(wCrc & 1){wCrc >> = 1; wCrc ^= 0xA001; }

wCrc >> = 1;

8

return wCrc;

3